

Overview

This project created a method for classroom students to vote for one of two choices at each moment in time while watching videos.

Outline of technique

- Students watch a video and signal two different judgments about the content by holding up two different colored cards.
- The instructor records a video of the class holding up the cards. The original video will be converted to a blurred version that preserves the color information (and thus the number of cards held up at each time point) but which obscures faces to protect students' identities.
- The instructor runs automated analysis code that produces a version of the video that the student watched, with an animated bar graph superimposed on it that displays the number of votes for both judgments at each point in time.
- The class can watch this video to understand and evaluate how the class voted as a whole, and discuss the accuracy or agreement of the judgments.

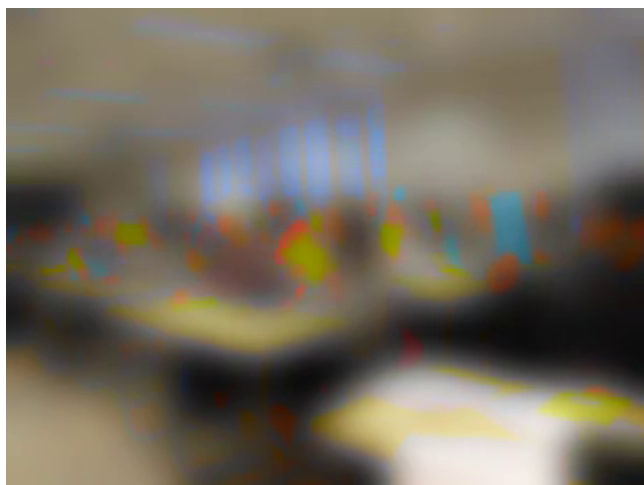
Illustration of the method

The class watches a video.

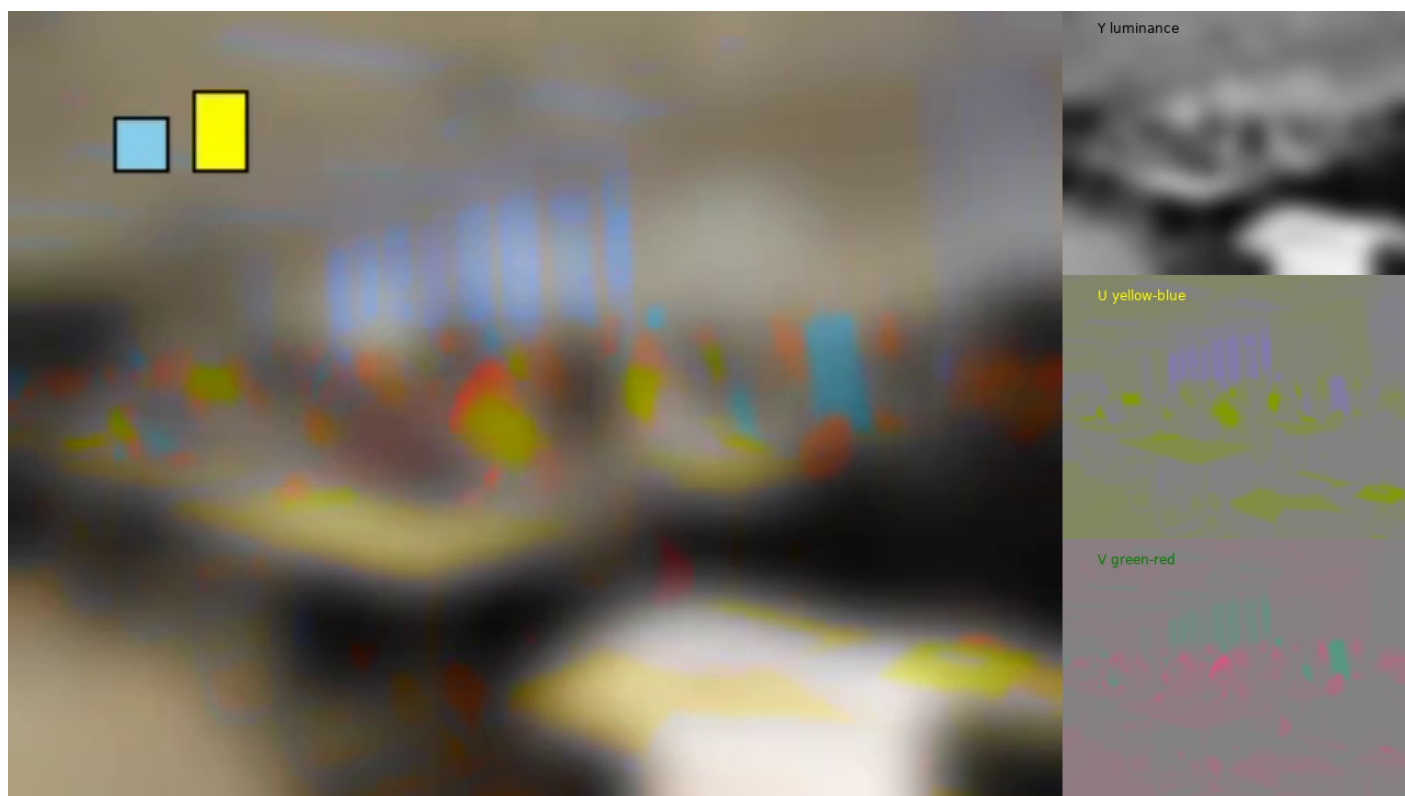


The instructor takes a video of the class to measure how many cards are held up at different points in

time. The luminance channel (black/white information) is immediately blurred so that students can't be identified. The color information is left unblurred.



The video is analyzed by splitting it into three component channels commonly used for encoding video.



The channel that measures yellow-blue differences (the U plane) is analyzed to get a count of how many yellow and blue cards the students hold up at each point in time.



To measure the amount of yellow and blue in the image, two different versions of the grayscale image are produced. One version includes all the pixels that fall below a specified threshold (yellow things) and another all the pixels that exceed a higher threshold (blue things). Both of these images are adjusted so that farther away parts of the scene count more than closer ones. This makes sure that farther away cards (which appear smaller in the images) count as much as closer ones.



The U plane, where dark values indicate yellow and bright one are for blue.

Create two new images that show the locations of yellow and blue things by selecting only the low or high values.

low thresholded image



high thresholded image

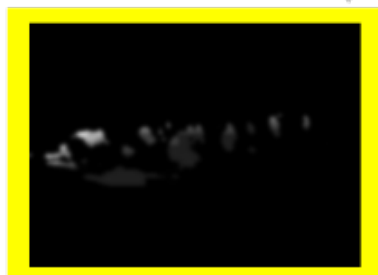


Crop the thresholded images to remove white pixels from the top and bottom portions. No cards ever appear in these parts of the frame, so there is no need to count how much yellow or blue is there.



Give locations close to the camera a smaller value than locations far away, by multiplying the thresholded images by this one.

This prevents close-up cards from counting more than far away cards. The transformation is defined by perspective projection.



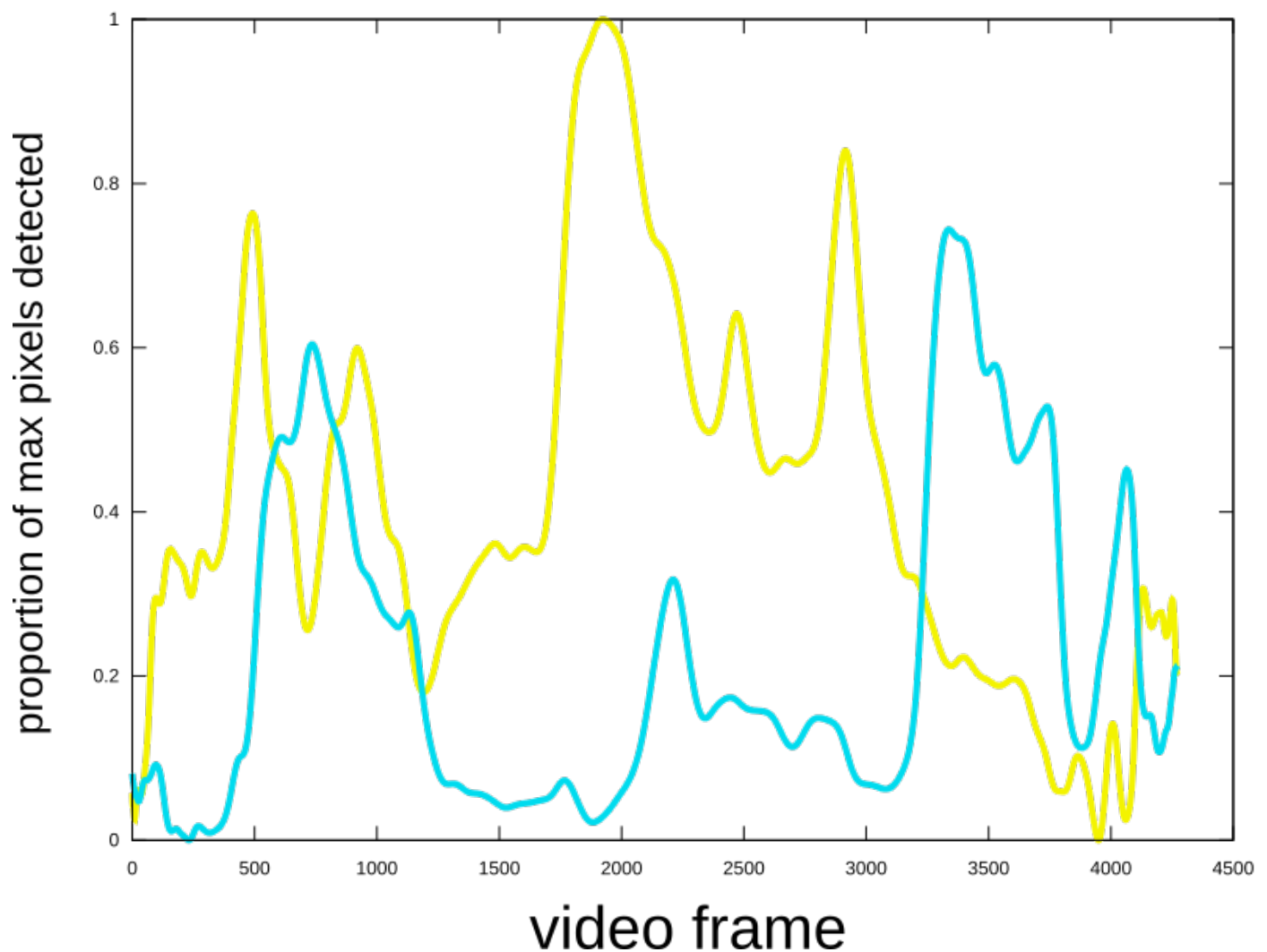
The pixel intensity values in each image can now be summed to give a measure of how many cards are being held up.

The amount of brightness (the pixel values) in each image is summed up, and these tallies stand for how many yellow and blue cards were visible at that point in time. One tally is made for every frame of the video, which means that there are about 30 tallies per second.

Some parts of the image correspond to yellow (the desks) and blue (the windows) things. However, these things don't change from second to second in the video, unlike the cards that students hold up. All of the tallies for all of the thousands of video frames are compared, and the minimum tally value is then subtracted from all frames' tallies. This subtracts away the baseline amount of yellow or blue that is constant across video frames.



The values of all the frames' tallies can then be normalized to lie on a scale between zero and one, and can be graphed like this. Higher values indicate when more cards were being held up.



The numbers in the line graph above are used to draw little bar graphs on top of each of the video frames, so that viewers can see how many cards of each color were held up at each moment.

In this example, students held up their yellow cards when they thought the movie camera was being physically moved around to create motion on the screen. They held up their blue cards when they thought that the camera was being pointed at different spots (panned) or when the zoom was being changed to create motion on the screen.



How it works

YUV video encoding

<https://en.wikipedia.org/wiki/YUV>

Trigonometry to scale the area of the cards

The transformation of U plane pixel values to account for distance from the camera is complex, but it is still just trigonometry. The person making the recording of the class needs to note the dimensions of the classroom, the position of the camera (including height off the ground), and the average height at which the cards were held up. Here is a screenshot of the code that performs the transformation, just to give a sense of the complexity.


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# Let's try assigning the visual angle equation to a variable, and then inserting it below.
# Combine the expressions for adjusting based on vis. angle of vertical (y) and horizontal (x) position (which adc wrote as independent equations) into
one expression.

# "ld(0)" returns the value for scaled Y pos stored by the command corresponding to the Y_STORE var.

VERT_VIS_ANG=" (atan((${CAMERA_HEIGHT})*tan(((atan(${MAX_DISTANCE})/(${CAMERA_HEIGHT}-1))-atan(${MIN_DISTANCE}/${CAMERA_HEIGHT}))*${CROP_TOP})/(${CROP_BOT}
-${CROP_TOP})-(atan(${MAX_DISTANCE})/(${CAMERA_HEIGHT}-1))-atan(${MIN_DISTANCE}/${CAMERA_HEIGHT}))*ld(0))/(${CROP_BOT}-${CROP_TOP})+atan(${MAX_DISTANCE}/(${
CAMERA_HEIGHT}-1)))/(${CAMERA_HEIGHT}-1))-atan(tan(((atan(${MAX_DISTANCE})/(${CAMERA_HEIGHT}-1))-atan(${MIN_DISTANCE}/${CAMERA_HEIGHT}))*${CROP_TOP})/(${C
ROP_BOT}-${CROP_TOP})-(atan(${MAX_DISTANCE})/(${CAMERA_HEIGHT}-1))-atan(${MIN_DISTANCE}/${CAMERA_HEIGHT}))*ld(0))/(${CROP_BOT}-${CROP_TOP})+atan(${MAX_DISTANC
E})/(${CAMERA_HEIGHT}-1))))^2";

# Baseline value (for Y Pos = 1) to divide vert vis ang by for normalization
VERT_VIS_ANG_BASE="(atan((${CAMERA_HEIGHT})*tan(((atan(${MAX_DISTANCE})/(${CAMERA_HEIGHT}-1))-atan(${MIN_DISTANCE}/${CAMERA_HEIGHT}))*${CROP_TOP})/(${CROP
BOT}-${CROP_TOP})-(atan(${MAX_DISTANCE})/(${CAMERA_HEIGHT}-1))-atan(${MIN_DISTANCE}/${CAMERA_HEIGHT}))*5)/(${CROP_BOT}-${CROP_TOP})+atan(${MAX_DISTANCE}/(
${CAMERA_HEIGHT}-1)))/(${CAMERA_HEIGHT}-1))-atan(tan(((atan(${MAX_DISTANCE})/(${CAMERA_HEIGHT}-1))-atan(${MIN_DISTANCE}/${CAMERA_HEIGHT}))*${CROP_TOP})/(${C
ROP_BOT}-${CROP_TOP})-(atan(${MAX_DISTANCE})/(${CAMERA_HEIGHT}-1))-atan(${MIN_DISTANCE}/${CAMERA_HEIGHT}))*5)/(${CROP_BOT}-${CROP_TOP})+atan(${MAX_DISTANC
E})/(${CAMERA_HEIGHT}-1))))^2";

# "ld(1)" returns the value for scaled X pos stored by the command corresponding to the X_STORE var.

HOR_VIS_ANG="abs(atan((1/2-${MID_DISTANCE})*tan((abs(atan((${CAMERA_LAT_POS}-${ROW_WIDTH})/${MID_DISTANCE}))-atan(${CAMERA_LAT_POS}/${MID_DISTANCE}))*${CRO
P_L})/(${CROP_R}-${CROP_L}))-ld(1)*abs(atan((${CAMERA_LAT_POS}-${ROW_WIDTH})/${MID_DISTANCE}))-atan(${CAMERA_LAT_POS}/${MID_DISTANCE}))/(${CROP_R}-${CROP_L
}))+atan((${CAMERA_LAT_POS}/${MID_DISTANCE}))/(${MID_DISTANCE}))-atan((-1/2-${MID_DISTANCE})*tan((abs(atan((${CAMERA_LAT_POS}-${ROW_WIDTH})/${MID_DISTANCE}))-ata
n((${CAMERA_LAT_POS}/${MID_DISTANCE}))*${CROP_L})/(${CROP_R}-${CROP_L}))-ld(1)*abs(atan((${CAMERA_LAT_POS}-${ROW_WIDTH})/${MID_DISTANCE}))-atan((${CAMERA_LAT_P
OS}/${MID_DISTANCE}))/(${CROP_R}-${CROP_L}))+atan((${CAMERA_LAT_POS}/${MID_DISTANCE}))/(${MID_DISTANCE})));";

# Baseline value (for X Pos = 1) to divide hor vis ang by for normalization
HOR_VIS_ANG_BASE="abs(atan((1/2-${MID_DISTANCE})*tan((abs(atan((${CAMERA_LAT_POS}-${ROW_WIDTH})/${MID_DISTANCE}))-atan(${CAMERA_LAT_POS}/${MID_DISTANC
E}))*${CROP_L})/(${CROP_R}-${CROP_L}))-ld(1)*abs(atan((${CAMERA_LAT_POS}-${ROW_WIDTH})/${MID_DISTANCE}))-atan((${CAMERA_LAT_POS}/${MID_DISTANCE}))/(${CROP_R}-${C
ROP_L}))+atan((${CAMERA_LAT_POS}/${MID_DISTANCE}))/(${MID_DISTANCE}))-atan((-1/2-${MID_DISTANCE})*tan((abs(atan((${CAMERA_LAT_POS}-${ROW_WIDTH})/${MID_DISTANC
E}))-atan((${CAMERA_LAT_POS}/${MID_DISTANCE}))*${CROP_L})/(${CROP_R}-${CROP_L}))-ld(1)*abs(atan((${CAMERA_LAT_POS}-${ROW_WIDTH})/${MID_DISTANCE}))-atan((${CAMERA_LA
T_POS}/${MID_DISTANCE}))/(${CROP_R}-${CROP_L}))+atan((${CAMERA_LAT_POS}/${MID_DISTANCE}))/(${MID_DISTANCE})))";

# "AtanGray" for arctangent, grayscale
# Use conditional (if) to mask out bottom of image (recall that Y values are zero at top, max at bottom)
# "if(a,b) implies "if not a, set equal to zero"
--:-- gen_frames.sh 42% L439 Git-master (Shell-script[sh])

```

What this method teaches

Color space

Difference between hue, saturation, and lightness

YUV video encoding

Blurring of lightness contrast but not hue and saturation

Circularity of hue space

Importance of baseline for experimental measures

Perspective projection

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<https://wiki.anthonycate.org/> - **Visual Cognitive Neuroscience**

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